

**GB** **b. Functions for control set**  
**Mode II above**

Switch for gyro:  
Backwards, the gyro is in heading-lock mode  
Forwards, the gyro is in normal gyro-operation

**Move the control extremely delicately!**

PIT

LCD-Display

3D Mode/Normal mode

PLT

Switch for Dualrate (100% > 70%) for channel 1, 2 und 4

Left joystick

Right joystick

CH3 trim adjustment

CH2 trim adjustment

CH4 trim adjustment

CH1 trim adjustment

Power switch

Crystal socket on the rear

Keylock - Lock/Locked

PIT: This switch that controls the settings for pitch adjustment. The starting setting should be with the knob set to the 10:00 o'clock position.

PLT: This is the pitch end point position knob. The initial setting should be set at 1:00 o'clock position.

Reverse switch on pitch

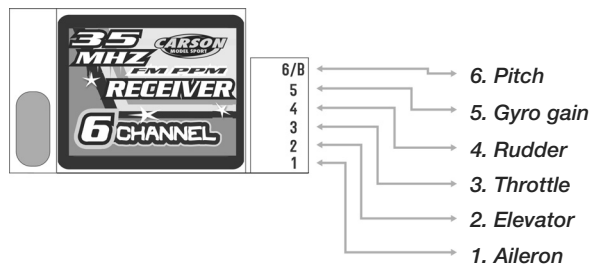
Reverse switch on tail rotor

Reverse switch on throttle

Reverse switch on nick

Reverse switch roll

**Picture of control set connection**



**c. Assembly Gyro:**

1. Ensure that the wireless remote controller and the servos are working perfectly and that the servo arms are in the correct position.
2. Attach the gyroscope in an absolutely horizontal position.
3. Plug the CH4 and CH5 servo connectors into the appropriate slots on the receiver. Attach the rear servo to the gyroscope.
4. Switch the transmitter on and centre the trimming lever to the middle. Connect the flight battery and wait until the LED on the gyroscope lights up. The gyroscope will then start a test run of the functions. The LED blinks for approx. 10 seconds and then stays alighted. The gyroscope is ready for operation. If not, you must check to ensure that the connections are ok and start the installation process over again.